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ideas, and the adopted notation of the book, and it previews the material in the later chapters.

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5. Let $B_1 = B_0 + 5 B_0 V_0 = [9.5 \ 1.00 \ -1.50]^T$. The object's position in $\{A\}$ is $T_{B_1}^A = A^T B_1 = [-4.89 \ 2.11 \ 3.60]$ 6.

(2.1) $R = \text{rot}(\hat{Y}, \varphi) \text{rot}(\hat{Z}, \theta) \begin{bmatrix} c\varphi & 0 & s\varphi \\ 0 & 1 & 0 \\ -s\varphi & 0 & c\varphi \end{bmatrix} \dots$

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